

# A REFINED RISK ASSESSMENT FRAMEWORK FOR AUTOMOTIVE



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## Introduction



# **Connected and autonomous** vehicles:

- Use of Artifical Intelligence (AI) based autonomous functionalities
- Increased connectivity beyond vehicle boundaries
- Significant increase in risks related to cyber-security
- Risk assessment is a pivotal and increasingly complex activity

## Introduction



### **Fuzzy logic based risk assessment**

- In line with the ISO/SAE 21434
- Provides output on a continuous scale, favouring risk prioritization and classification
- Explicitly models incomplete or imprecise input data
- Preserves the explainability of the process

• Introduction

#### • Fuzzy Logic Basics

- Risk Assessment Framework
- Application Example
- Conclusions

# What is fuzzy logic

• Fuzzy logic is a way to model logical reasoning where the truth of a statement is not binary



### **Fuzzy Inference System**



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### **Framework Overview**

- Takes place during TARA, after damage and threat scenarios have been identified
- The input variables that determine the risk are *Feasibility Rating* and *Impact Rating*





## **Membership functions**

Membership functions are used to map the input space to a degree of truth between 0 and 1 for a set of human interpretable labels

#### **Feasibility Rating**

Calculated with CVSS  $\rightarrow$  input range [0.12, 3.89]

#### **Discrete Mapping**

Classic reasoning

#### Membership functions Fuzzy reasoning

Input Interval	Label	
2.96 – 3.89	High	
2.00 – 2.95	Medium	
1.06 – 1.99	Low	
0.12 - 1.05	Very Low	



## Rule base

#### **Feasibility rating** Very Low Medium Low High 2 3 4 5 Severe Major 2 1 3 4 Impact rating Moderate 1 2 2 3 Negligible 1 1 1 1

**Risk Matrix** 



#### **Rule Base**

		Feasibility rating			
		Very Low	Low	Medium	High
	Severe	Low	Medium	High	Very High
Impact	Major	Very Low	Low	Medium	High
rating	Moderate	Very Low	Low	Low	Medium
	Negligible	Very Low	Very Low	Very Low	Very Low

IF Impact Rating is Severe AND Feasibility Rating is Very Low THEN Risk is Low

IF Impact Rating is Severe AND Feasibility Rating is Very Low THEN Risk is Medium

## MATLAB Fuzzy Logic Designer

#### Membership functions



#### Rule base

Syster	n: RiskAssessmentProposal			
Add A	II Possible Rules) (Clear All Rules)			
	Rule	Weight	Name	
1	If Feasibility Rating is Very Low and Impact Rating is Negligible then Risk is Very Low	1	rule1	
2	If Feasibility Rating is Low and Impact Rating is Negligible then Risk is Very Low	1	rule2	
3	If Feasibility Rating is Medium and Impact Rating is Negligible then Risk is Very Low			
4	If Feasibility Rating is Very Low and Impact Rating is Moderate then Risk is Very Low			
5	If Feasibility Rating is Low and Impact Rating is Moderate then Risk is Low	1	rule5	
6	If Feasibility Rating is Medium and Impact Rating is Moderate then Risk is Low	1	rule6	
7	If Feasibility Rating is Very Low and Impact Rating is Major then Risk is Very Low	1	rule7	
8	If Feasibility Rating is Low and Impact Rating is Major then Risk is Low	1	rule8	
9	If Feasibility Rating is Medium and Impact Rating is Major then Risk is Medium			
10	If Feasibility Rating is Very Low and Impact Rating is Severe then Risk is Low	1	rule10	
11	If Feasibility Rating is Low and Impact Rating is Severe then Risk is Medium	1	rule11	
12	If Feasibility Rating is Medium and Impact Rating is Severe then Risk is High	1	rule12	
13	If Feasibility Rating is High and Impact Rating is Negligible then Risk is Very Low	1	rule13	
14	If Feasibility Rating is High and Impact Rating is Moderate then Risk is Medium	1	rule14	
15	If Feasibility Rating is High and Impact Rating is Major then Risk is High	1	rule15	
16	If Feasibility Rating is High and Impact Rating is Severe then Risk is Very High	1	rule16	

#### **Complete System**



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## **Application example**



#### **Headlamp System**

#### **Damage Scenario:**

Front collision with a narrow stationary object (e.g. a tree) caused by unintended turning-off of headlamp during night driving at *low speed* (<30 km/h) and *icy road surface*.

#### **Threat Scenario:**

Tampering with a signal sent by body control ECU leads to loss of integrity of the data communication of the "Lamp Request" signal to the power switch actuator ECU, potentially causing the headlamp to turn off unintentionally.

## **Example Risk Calculation**





Threat scenario	Damage Scenario	FIS Result	ISO/SAE 21434 Result
	1	5.00	5
	2	4.00	4
1	3	4.41	4
	4	4.41	4
	5	3.50	4
	1	3.94	4
	2	2.94	3
2	3	3.44	3
	4	3.44	3
	5	2.50	3

- Results are generally in line with the standard proposed method
- Output is on a continuous scale instead of a discrete one
- Allows to capture differences in risks that would have the same value according to the traidional method

Threat scenario	Damage Scenario	FIS Result	ISO/SAE 21434 Result
	1	5.00	5
	2	4.00	4
1	3	4.41	4
	4	4.41	4
	5	3.50	4
	1	3.94	4
	2	2.94	3
2	3	3.44	3
	4	3.44	3
	5	2.50	3

- Results are generally in line with the standard proposed method
- Output is on a continuous scale instead of a discrete one
- Allows to capture differences in risks that would have the same value according to the traidional method

## Advantages

- The risk surface is smoother, which indicates a finer level of detail in terms of risk calculation
- The methodology preserves the linear ordering among the risks calculated with it



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## Conclusions

The proposed **fuzzy-logic-based framework** aims to bring some advantages to the risk assessment procedure while remaining within the scope of the TARA process. Its key features are:

- Increased granularity in the risk output (continuous scale)
- Allows to differentiate between risks that would have the same value otherwise
- Capability of handling a certain **degree of uncertainty**
- Flexibility & minimal overhead thanks to tools support